Rudraksh Kapil

HIGHLIGHT OF SKILLS

A motivated M.Sc. CS developer skilled in deep/machine learning, computer vision, programming, research, and collaboration. **ML Expertise**: 3+ YoE developing novel, SOTA deep models trained on large datasets to solve real-world problems: 5 papers. Technologies: Proficient in Python + PyTorch, scikit, OpenCV, etc.; Exp. w/ LLMs, AWS SageMaker, C++, C#, Java, JS, SQL, Git. Communication: Weekly presentations in multi-discipline (ML & non-ML) research groups, participation in conferences, teaching.

FDUCATION

M.Sc. in Computer Science

University of Alberta (UofA)

- Thesis: Advancing Forest Health Monitoring: Harnessing the Power of Deep Learning Computer Vision for Remote Sensing
- Relevant Courses: 3D Computer Vision, Statistical Methods for ML, Privacy and Fairness in ML, Research Methods.
- GPA: 4.0/4.0 · Awards: (1) Outstanding Thesis, (2) Anina Hundsdoerfer Scholarship (3) Full-funding from CS Department.

B.Tech. in Computer Science & Engineering

National Institute of Technology, Warangal

- Relevant Courses: Data Structures and Algorithms, Object-oriented Programming, Systems Design, Software Engineering.
- GPA: 8.87 / 10 First Division with Distinction (Top 10%) & received entrance scholarship for academic excellence.
- GRE: 338/340 170 Quantitative, 168 Verbal, 5.5/6.0 Analytical Writing and Analysis. TOEFL: 120/120.

WORK EXPERIENCE

ML/DL Developer (Remote Sensing) – Natural Resources Canada (Federal Govt.)

- Developed a DSM-based open-source tool to project bounding boxes from drone images to geo-located polygons in GIS.
- Leveraged 3D computer vision & depth estimation through ray-tracing to achieve projection with >95% accuracy.
- Designed a YOLOv8-based detector for Ash trees from a city-wide orthomosaic of Edmonton with 70% average precision.
- Presented progress updates to senior research scientists and tailor code implementation according to 'client' feedback.

Skills: Python, PyTorch, Object detection, Drone remote sensing, GIS, Agisoft, Pix4D, ODM, 3D computer vision, LiDAR point clouds.

ML/DL Researcher – Prof. Nilanjan Ray's Vision and Robotics Lab, UofA

- Conducted cross-disciplinary research to solve undefined problems with a group of 4 from the forestry department and NRCan.
- Specialized in deep learning computer vision applied to forest health management with RGB-thermal drone/satellite imagery.
- Delivered presentations on latest research findings during bi-weekly update meetings of 15-member group.

Skills: Python, PyTorch, TensorFlow, OpenCV, NumPy, Pandas, scikit-learn, scikit-image, seaborn, R, Git, Pandas, Research, CNNs, Presentation, Object detection, Multi-modal fusion, Video tracking, Species classification, Transfer learning, Self-supervised learning.

Lead Student Instructor – CS Department, UofA

- Managed the Content Support functional team of 5 Teaching Assistants (TAs) for a Python intro course of 1000+ students.
- Supervised weekly meetings for progress updates and training first-time TAs on pedagogy and carrying out functional tasks.
- Reviewed 15 lab assignments, 10 quizzes, and 16 sets of lecture slides to proactively identify issues and improve content.
- Taught core coding concepts during labs to 40+ students. Marked 100s of assignments and provided 1-1 feedback for all.
- Received role based on exemplary performance as regular TA during previous 2 semesters for various courses.

Skills: Python, Content creation, Quality control, Teaching, Mentoring, Code review, Team management, Collaboration, Delegation.

Lead Programmer – GBit Studios Game Development

- Spearheaded the production of 4 new Unity (C#) & Android (Java) games published to the Apple & Google Stores Agile team.
- Interviewed and trained 50+ prospective recruits by hosting tutorial classes and 1-1 sessions to selected 5 candidates.

• Trained an autonomous AI system via reinforcement learning using Unity ML Agents for simulating realistic enemy behavior.

Skills: Unity, C#, C++, Java, Android Studio, Swift + Xcode, Project management, Data structures, Object-oriented programming.

Product Development Intern – Smart Content Team, Oracle

- Developed 2 models to compute color distribution of imaged objects segmented by Mask R-CNN with 98% accuracy.
- Integrated these into Oracle's Content Management System to enhance the visual search engine via tagging automation.
- Awarded 2nd place in the Oracle All-India Interns' Hackathon alongside two teammates by top ranking executives.
- Received a full time employment offer from Oracle based on exceptional performance, 1 year in advance of graduating.

Skills: Python, Jupyter, Oracle databases, SQL, PL/SQL, Unix Shell, Javascript, HTML, CSS, XML, JSON.

SEP 2021 - AUG 2023

SEP 2017 - APR 2021

JUL 2023 - PRESENT

SEP 2022 - DEC 2022

SEP 2021 - AUG 2023

JUL 2020 - AUG 2020

JAN 2019 - JUN 2021

ML/DL PUBLICATIONS

All are publicly available. For abstracts and links to each, kindly refer to my website.

Skills: Experimental evaluation • Devising and training SOTA DL methods • Optimization • Handling large datasets (preprocessing, cleaning, labeling, visualization) • Reading & writing (LaTeX) academic papers • Presenting & networking at conferences • Visualizing via figures • Identifying & solving practical problems creatively • Leadership & collaboration • Project & time management • Organization.

- [1] R. Kapil, S. M. Marvasti-Zadeh, N. Erbilgin, and N. Ray, "Shadowsense: Unsupervised domain adaptation and feature fusion for shadow-agnostic tree crown detection from rgb-thermal drone imagery," in Proceedings of the IEEE/CVF Winter Conference on Applications of Computer Vision (WACV), January 2024. In print.
- [2] R. Kapil, G. Castilla, S. M. Marvasti-Zadeh, D. Goodsman, N. Erbilgin, and N. Ray, "Orthomosaicking thermal drone images of forests via simultaneously acquired RGB images," MDPI Remote Sensing Journal, Featured Paper, vol. 15, no. 10, p. 2653, 2023.
- [3] R. Kapil, S. M. Marvasti-Zadeh, D. W. Goodsman, N. Ray, and N. Erbilgin, "Classification of bark beetle-induced forest tree mortality using deep learning," in Visual observation and analysis of Vertebrate And Insect Behavior Workshop at ICPR, 2022.
- [4] S. Gupta, R. Kapil, G. Kanahasabai, S. S. Joshi, and A. S. Joshi, "SD-Measure: a social distancing detector," in IEEE 12th International Conference on Computational Intelligence and Communication Networks (CICN), pp. 306–311, 2020.
- [5] A. S. Joshi, S. S. Joshi, G. Kanahasabai, R. Kapil, and S. Gupta, "Deep learning framework to detect face masks from video footage," in IEEE 12th International Conference on Computational Intelligence and Communication Networks (CICN), pp. 435–440, 2020.

RELEVANT PROJECTS

For an extended list, kindly refer to my website.

Predictive Display for Robotic Arm Tele-operation

• Accomplished dynamic texturing of a simulated 3D environment to overcome communication delay in robotic tele-operation. Skills: MATLAB, Python, C++, ROS, ORB-SLAM, OpenSfM, CARV 3D Reconstruction, Ubuntu, OpenCV, Eigen, Pangolin, Unity 3D, C#

AWS SageMaker Projects

(1) Image classification model [ICPR] deployed as: (i) pre-trained inference endpoint; (ii) trained w/ transfer learning & custom data. (2) BERT model for sentiment classification: fine-tuned transfer learning, k-fold cross validation, cloud-deployed inference model. Skills: AWS SageMaker, Python, Cloud deployment, Natural language processing, BERT, LLMs, GPT, RetinaNet, RCNN, CUDA, Spark.

Privacy, Fairness, and Equity of GAN-generated Data

• Investigated the relationships and tradeoffs between privacy, fairness, and utility in GAN-generated synthetic tabular data. Skills: Python, PyTorch, TensorFlow, scikit-learn, Encoders, Jupyter, NumPy, pandas, Deep GAN models, Differential privacy.

Selected Unity Applications: (1) Flick To Kick Rugby, (2) Maximum Velocity

- Published games, each with >1000 installs on iOS and Google Play (Android).
 - Programmed various gameplay physics mechanics and necessary systems like menu and shop navigation.
 - Designed several 3D models, particle systems, and animations using Maya/Blender and integrated these into the games.
 - Skills: C#, Unity, Swift, Xcode, Scripting, Graphics, Maya, Blender, UI/UX, Animation, Scripting, Multi-media/platform dev., Testing.

Android Application: Revenge of the Sudoku

Published game with >1000 installs on Google Play (Android).

• Developed novel game independently on Android Studio with Java and published it to Play Store.

Skills: Java, Android Studio, Kotlin, CSS, XML, JSON, IntelliJ, Javascript, Backtracking, Emulators, APIs, UI/UX design, Deployment.

Open-source Thermal Orthomosaicking GUI Tool

Already being used by remote sensing researchers in Alberta, Sydney, and South Wales.

- Packaged the proposed algorithm in my MDPI paper as a Windows GUI tool to facilitate easy use and further improvement.
- Skills: Python, bash, PyQt5 & Designer, Docker, Git, CI/CD, CUDA, OpenDroneMap, OpenSfM, OpenMVS, WSL, MeshLab, GDAL.

Image to GIS (& vice versa) Projection Tool

• Developed an open-source tool to map boxes from local drone image space to specified global projection space (e.g., UTM). Skills: Python, rasterio, pyshp, GIS, 3D computer vision, Ray-tracing, Computer graphics, Linear algebra, Computational geometry.

Attentive-normalized Image Generation

 Improved a deep network that generates images from layouts by using attentive normalization to enhance photo-realism. Skills: Python, PyTorch, and Deep CNN-based GANs, Git, CI/CD, Technical writing, LaTeX, Presentation.

Backpropamine - Research Paper Implementation

• Implemented a self-modifying RNN with differentiable neuro-modulated plasticity to speed-up AI maze navigation by 20%. Skills: C++, Python, AI, OpenGL, Reinforcement learning, Research, Version control, Visualization, Technical documentation, LaTeX.

JAVA APP DEVELOPMENT

APP DEVELOPMENT

BACHELOR'S THESIS

REINFORCEMENT LEARNING

NRCAN PROJECT

2/2

GRADUATE COURSE PROJECT (3D CV)

CLOUD-DEPLOYED NLP & COMPUTER VISION MODELS

GRADUATE COURSE PROJECT (P&F IN ML)

RESEARCH CODE RELEASE